

Tutorial on Conflict-Driven Pseudo-Boolean Optimization

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SAT + SMT Winter School
Chennai, India
December 15, 2022

Outline of Tutorial on Pseudo-Boolean Optimization

- 1 MaxSAT and Pseudo-Boolean Optimization
 - Problem Definition
 - MaxSAT Solving
- 2 Linear Search SAT-UNSAT (LSU)
 - The Algorithm
 - Some More Details
- 3 UNSAT-SAT Search
 - Core-Guided Search
 - Implicit Hitting Set (IHS) Algorithm
 - Some Open Problems

MaxSAT Problem

Pseudo-Boolean optimization and MaxSAT solving intimately connected, so let's start by describing the MaxSAT problem

Weighted partial MaxSAT problem

Input: Soft clauses C_1, \dots, C_m with weights $w_i \in \mathbb{N}^+$, $i \in [m]$
Hard clauses C_{m+1}, \dots, C_M

Goal: Find assignment ρ such that

- for all hard clauses C_{m+1}, \dots, C_M it holds that $\rho(C_j) = 1$
- ρ maximizes $\sum_{\rho(C_i)=1, i \in [m]} w_i$

- All hard clauses **must** be satisfied
- Maximize weight of satisfied soft clauses =
Minimize penalty of falsified soft clauses
- Write $(C)_w$ for clause C with weight w ($w = \infty$ for hard clause)

From MaxSAT to Pseudo-Boolean Optimization

MaxSAT instance

$$(\bar{x})_5$$

$$(y \vee \bar{z})_4$$

$$(\bar{y} \vee z)_3$$

$$(x \vee y \vee z)_\infty$$

$$(x \vee \bar{y} \vee \bar{z})_\infty$$

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PBO instance

$$\min 5b_1 + 4b_2 + 3b_3$$

$$b_1 + \bar{x} \geq 1$$

$$b_2 + y + \bar{z} \geq 1$$

$$b_3 + \bar{y} + z \geq 1$$

$$x + y + z \geq 1$$

$$x + \bar{y} + \bar{z} \geq 1$$

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So-called **blocking variable transformation**
Variables b_i are **blocking** or **relaxation variables**

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So-called **blocking variable transformation**

Variables b_i are **blocking** or **relaxation variables**

Optimal solution $\rho = \{x = 0, y = 1, z = 0\}$ with **penalty 3**

From Pseudo-Boolean Optimization to MaxSAT/WBO

“MaxSAT instance” but with PB constraints:
Weighted Boolean Optimization [MMP09]

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$$C_1$$
$$C_2$$
$$\vdots$$
$$C_M$$

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C_1

C_2

\vdots

C_M

MaxSAT/WBO instance

$(\bar{\ell}_1)_{w_1}$

\vdots

$(\bar{\ell}_n)_{w_n}$

$(C_1)_\infty$

\vdots

$(C_M)_\infty$

Flavours of MaxSAT

- **Partial MaxSAT**: Hard and soft clauses
- **MaxSAT**: Only soft clauses
- **Unweighted MaxSAT**: Same weight for soft clauses (w.l.o.g. 1)
- **Weighted MaxSAT**: Different weights for soft clauses

4 different subproblems

But most current solvers deal with the most general problem

Main Approaches for MaxSAT Solving (and PBO)

- 1 Linear search SAT-UNSAT (LSU) (or model-improving search)
- 2 Core-guided search
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Will describe all of these algorithms as trying to

- minimize $\sum_{i=1}^n w_i l_i$
- subject to collection of PB constraints $F = C_1 \wedge \dots \wedge C_m$
(possibly clausal)

Linear Search SAT-UNSAT (LSU) Algorithm

- Minimize $\sum_{i=1}^n w_i l_i$
- Subject to collection of PB constraints $F = C_1 \wedge \dots \wedge C_m$

Set $\rho_{\text{best}} = \emptyset$ and repeat the following:

- 1 Run SAT/PB solver
- 2 If solver returns **UNSATISFIABLE**, output ρ_{best} and terminate
- 3 Otherwise, let $\rho_{\text{best}} :=$ returned solution ρ
- 4 Add **solution-improving** constraint
$$\sum_{i=1}^n w_i l_i \leq -1 + \sum_{i=1}^n w_i \cdot \rho(l_i)$$
- 5 Start over from the top

Linear Search Toy Example

- 1 Given PB formula F and objective function
 $\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6$

Linear Search Toy Example

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- 2 Solver run on F returns $\rho_1 = \{x_1 = x_2 = x_3 = x_6 = 0; x_4 = x_5 = 1\}$
- 3 Yields objective value $0 + 2 \cdot 0 + 3 \cdot 0 + 4 \cdot 1 + 5 \cdot 1 + 6 \cdot 0 = 9$, so add

$$x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6 \leq 8$$

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- 4 Solver run on F plus this new constraint returns
 $\rho_2 = \{x_1 = x_3 = x_5 = x_6 = 0; x_2 = x_4 = 1\}$

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$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6$$

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- ④ Solver run on F plus this new constraint returns

$$\rho_2 = \{x_1 = x_3 = x_5 = x_6 = 0; x_2 = x_4 = 1\}$$

- ⑤ Yields objective value 6, so add

$$x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6 \leq 5$$

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- ⑦ Hence, **minimum value** of objective function subject to F is **6**

CNF Encoding of Solution-Improving Constraint

For SAT solver, need CNF encoding of solution-improving constraint

$$\sum_{i=1}^n w_i l_i \leq -1 + \sum_{i=1}^n w_i \cdot \rho(l_i)$$

Lots of work on how to do this in smart ways (with encodings like [PRB18] being current state of the art)

For pseudo-Boolean solver, no re-encoding needed
Solution-improving constraint can be added as is

Linear vs. Binary Search?

What if we run [binary search](#) instead of linear search?

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Two possible explanations:

- 1 In theory, objective value could decrease by just 1 every time — in practice, tend to get much larger jumps
- 2 Potentially very different cost for
 - SAT calls (feasible instances where solver will find solution)
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Properties of linear search SAT-UNSAT:

- Can get **some decent** solution quickly, even if not optimal one
- Important for **anytime solving** (when time is limited and something is better than nothing)
- But get no estimate of how good the solution is

Quick Detour: Running Solvers with Assumptions

Given

- CNF or PB formula F
- partial assignment ρ

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Solver outputs

- either **solution** extending ρ
- or **explanation** (clause/pseudo-Boolean inequality) why assumptions ρ inconsistent with F

Explanation obtained by simple modification of conflict analysis
(**decision learning scheme**)

Core-Guided Search

- Minimize $\sum_{i=1}^n w_i l_i$
- Subject to collection of PB constraints $F = C_1 \wedge \dots \wedge C_m$

Think first of this as MaxSAT instance with l_i as blocking variables

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- 6 Update objective function and val_{best} using $\sum_{i=1}^k l_i = 1 + \sum_{j=2}^k z_j$ to cancel at least one literal l_i

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- 7 Start over from top with updated objective function

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- Original core-guided idea from [FM06]; see [MHL⁺13] for survey

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- And rewriting very convenient — just use PB constraints without re-encoding
- **Core-guided PB search**: assume optimistically that objective can reach best imaginable value; derive contradiction if not possible
- Let us try to explain by concrete example

Core-Guided Search Toy Example (1/5)

- ① Given same **PB formula F** and objective function

$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6 \quad (1)$$

Core-Guided Search Toy Example (1/5)

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$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6 \quad (1)$$

- 2 Set $val_{\text{best}} = 0$

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- 1 Given same **PB formula F** and objective function

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- 3 Run solver on F with assumptions $x_1 = x_2 = \dots = x_6 = 0$

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$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6 \quad (1)$$

- 2 Set $val_{\text{best}} = 0$
- 3 Run solver on F with assumptions $x_1 = x_2 = \dots = x_6 = 0$
- 4 Suppose solver returns **PB core constraint**

$$3x_2 + 2x_3 + x_4 + x_5 \geq 4 \quad (2)$$

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$$3x_2 + 2x_3 + x_4 + x_5 \geq 4 \quad (2)$$

- 5 Round to nicer-to-work-with **cardinality core constraint**

$$x_2 + x_3 + x_4 + x_5 \geq 2 \quad (3)$$

Core-Guided Search Toy Example (1/5)

- 1 Given same **PB formula F** and objective function

$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6 \quad (1)$$

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- 5 Round to nicer-to-work-with **cardinality core constraint**

$$x_2 + x_3 + x_4 + x_5 \geq 2 \quad (3)$$

- 6 Introduce new, fresh variables y_3 and y_4 and constraints

$$x_2 + x_3 + x_4 + x_5 = 2 + y_3 + y_4 \quad (4a)$$

$$y_3 \geq y_4 \quad (4b)$$

to enforce that y_j means " $x_2 + x_3 + x_4 + x_5 \geq j$ "

Core-Guided Search Toy Example (2/5)

- ⑦ Multiply (4a) by 2 to get

$$4 + 2y_3 + 2y_4 - 2x_2 - 2x_3 - 2x_4 - 2x_5 = 0$$

and add to objective function

$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6$$

in (1) to cancel x_2 and get updated, equivalent objective function

$$\min x_1 + x_3 + 2x_4 + 3x_5 + 6x_6 + 2y_3 + 2y_4 + 4 \quad (5)$$

Core-Guided Search Toy Example (2/5)

- 7 Multiply (4a) by 2 to get

$$4 + 2y_3 + 2y_4 - 2x_2 - 2x_3 - 2x_4 - 2x_5 = 0$$

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$$\min x_1 + x_3 + 2x_4 + 3x_5 + 6x_6 + 2y_3 + 2y_4 + 4 \quad (5)$$

- 8 Update $val_{\text{best}} = 4$

Core-Guided Search Toy Example (2/5)

- 7 Multiply (4a) by 2 to get

$$4 + 2y_3 + 2y_4 - 2x_2 - 2x_3 - 2x_4 - 2x_5 = 0$$

and add to objective function

$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6$$

in (1) to cancel x_2 and get updated, equivalent objective function

$$\min x_1 + x_3 + 2x_4 + 3x_5 + 6x_6 + 2y_3 + 2y_4 + 4 \quad (5)$$

- 8 Update $val_{\text{best}} = 4$
- 9 Run solver on F assuming all literals in (5) being 0

Core-Guided Search Toy Example (3/5)

- ⑩ Suppose solver returns the clausal core constraint

$$x_4 + x_5 + x_6 + y_3 \geq 1 \quad (6)$$

Core-Guided Search Toy Example (3/5)

- 10 Suppose solver returns the clausal core constraint

$$x_4 + x_5 + x_6 + y_3 \geq 1 \quad (6)$$

- 11 Introduce new variables z_2, z_3, z_4 and the constraints

$$x_4 + x_5 + x_6 + y_3 = 1 + z_2 + z_3 + z_4 \quad (7a)$$

$$z_2 \geq z_3 \quad (7b)$$

$$z_3 \geq z_4 \quad (7c)$$

to enforce that z_j means “ $x_4 + x_5 + x_6 + y_3 \geq j$ ”

Core-Guided Search Toy Example (4/5)

- 12 Multiply (7a) by 2 to get

$$2 + 2z_2 + 2z_3 + 2z_4 - 2x_4 - 2x_5 - 2x_6 - 2y_3 = 0$$

and add to rewritten objective

$$\min x_1 + x_3 + 2x_4 + 3x_5 + 6x_6 + 2y_3 + 2y_4 + 4$$

in (5) to get 3rd equivalent objective

$$\min x_1 + x_3 + x_5 + 4x_6 + 2y_4 + 2z_2 + 2z_3 + 2z_4 + 6 \quad (8)$$

Core-Guided Search Toy Example (4/5)

- 12 Multiply (7a) by 2 to get

$$2 + 2z_2 + 2z_3 + 2z_4 - 2x_4 - 2x_5 - 2x_6 - 2y_3 = 0$$

and add to rewritten objective

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Core-Guided Search Toy Example (4/5)

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- 13 Update $val_{\text{best}} = 6$
- 14 For 3rd time run solver on F , assuming all literals in (8) being 0

Core-Guided Search Toy Example (5/5)

- 15 Suppose solver reports it is possible to achieve

$$\rho = \{x_1 = x_3 = x_5 = x_6 = y_4 = z_2 = z_3 = z_4 = 0\} \quad (9)$$

Core-Guided Search Toy Example (5/5)

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- 16 Under assignment (9) the equality (4a) simplifies to

$$x_2 + x_4 = 2 + y_3 \quad (10)$$

which can hold only if $y_3 = 0$ and $x_2 = x_4 = 1$, and this also satisfies (7a).

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- 17 Hence, have recovered optimal solution yielding objective value 6 (as in LSU example before)

Properties of (Pure) Core-Guided Search

- Can get decent lower bounds on solution quickly
- Helps to cut off parts of search space “too good to be true”
- But find no actual solution until the final, optimal one
- Also, no estimate of how good the lower bound is
- Linear search much better at finding solutions — how to get the best of both worlds?

Improvements of Core-Guided Search (1/2)

Weight stratification [ABGL12]

Set only literals with largest weight in objective to 0 \Rightarrow

- 1 More compact core; or
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Start with core-guided search to get good lower bound estimate; then switch to linear search to find optimal solution

Hybrid/interleaving search [ADMR15]

Switch back and forth repeatedly between core-guided and linear search — cumbersome in CNF-based solver, but fairly cheap (and efficient) in native pseudo-Boolean solver [DGD⁺21]

Improvements of Core-Guided Search (2/2)

Core minimization (e.g., [Mar10, MIM15])

In CDCL-based solver, try to get smaller core clauses. For PB solver, not so clear how to do this (constraint minimization also interesting problem in general for PB conflict analysis)

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Lazy variables [MJML14, DGD⁺21]

For real-world instances, rewriting of objective function can introduce huge numbers of new variables, slowing down the solver — so don't introduce all variables in one go but only lazily as needed

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Inference strength of core-guided search?

- **Extension variables** very strong in theory, but hard to use in practice
- Core-guided search provides principled way of introducing them
- Can we characterize the power of this method?

Evaluation of Core-Guided PB Solver in [DGD⁺21]

ROUNDINGSAT with core-guided (CG) and linear search (LSU)

#instances solved to optimality; highlighting **1st**, **2nd**, and **3rd** best

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	PB16opt (1600)	MIPopt (291)	KNAP (783)	CRAFT (985)
HYBRID (interleave CG & LSU)	968	78	306	639
HYBRIDCL (w/ clausal cores)	937	75	298	618
HYBRIDNL (w/ non-lazy variables)	936	70	186	607
HYBRIDCLNL (w/ both)	917	67	203	612
ROUNDINGSAT (only LSU)	853	75	341	309
COREGUIDED (only CG)	911	61	43	595
COREBOOSTED (10% CG, then LSU)	959	80	344	580
SAT4J	773	61	373	105
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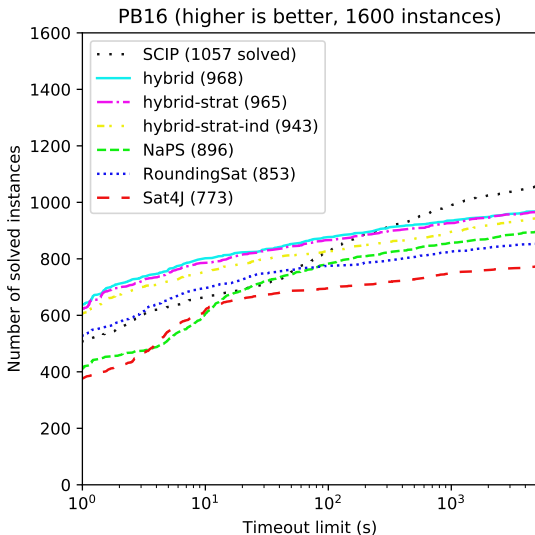
Significant improvement over PB state of the art, but MIP still better

Core-Guided PB Solving for PB16 benchmarks [DGD⁺21]

Cumulative plot for solver performance on PB16 optimization benchmarks

Also including

- weight stratification (**strat**)
- disjoint/independent cores (**ind**)



Implicit Hitting Set (IHS) Algorithm (1/2)

- Minimize $\sum_{i=1}^n w_i l_i$
- Subject to collection of PB constraints $F = C_1 \wedge \dots \wedge C_m$
(consider clausal constraints)

As in core-guided search, use solving with assumptions, but maintain collection \mathcal{K} of learned core clauses

$$C_1 \doteq l_{1,1} \vee l_{1,2} \vee \dots \vee l_{1,k_s}$$

$$C_2 \doteq l_{2,1} \vee l_{2,2} \vee \dots \vee l_{2,k_s}$$

$$\vdots$$

$$C_s \doteq l_{s,1} \vee l_{s,2} \vee \dots \vee l_{s,k_s}$$

Implicit Hitting Set (IHS) Algorithm (2/2)

Set $\mathcal{K} = \emptyset$ and repeat the following:

- 1 Run optimization solver to compute **minimum hitting set** for \mathcal{K} , i.e., $H = \{l_i\}$ s.t.
 - $H \cap C \neq \emptyset$ for all $C \in \mathcal{K}$ (H is **hitting set**)
 - $\sum_{l_i \in H} w_i$ minimal among H with this property.
- 2 Run decision solver on F with assumptions $\{l_j = 0 \mid l_j \notin H\}$
- 3 If decision solver found solution, it must be optimal (since hitting set is optimal), so return solution with value $\sum_{l_i \in H} w_i$
- 4 Otherwise, decision solver returns new core C_{s+1} — add it to \mathcal{K} and start over from top

More About the Hitting Sets

- Minimality is actually not needed except in the very final step
- Save time by computing “decent” hitting sets earlier on in the search
- How to find hitting set?
- This is itself a pseudo-Boolean optimization problem
 - Run IP solver [standard approach]
 - Or PB solver?
 - Or local search?!

Combine IHS with Pseudo-Boolean Optimization?

IHS and PB Optimization

- In PB setting, cores will not be subsets of clauses but PB constraints C_1, \dots, C_s over objective function literals
- “Hitting set” H is partial assignment guaranteed to satisfy all constraints C_1, \dots, C_s
- Want to find minimum-cost set H of literals (w.r.t. objective function) with this property

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-
- Explored by CoReO group in Helsinki in [SBJ21, SBJ22]
 - Using ROUNDINGSAT version in [DGN21] as pseudo-Boolean decision solver

IHS Algorithm for PB Optimization (Simplified)

- Minimize $\sum_{i=1}^n w_i l_i$
- Subject to collection of PB constraints $F = C_1 \wedge \dots \wedge C_m$

Set $\mathcal{K} = \emptyset$ and repeat the following:

- 1 Run optimization solver to minimize $\sum_{i=1}^n w_i l_i$ under \mathcal{K} , yielding solution ρ to objective variables
- 2 Run decision solver with assumptions ρ on decision problem F
- 3 If decision solver returns **SATISFIABLE**, we have found optimal solution extending ρ with value $\sum_{i=1}^n w_i \cdot \rho(l_i)$
- 4 Otherwise, decision solver returns new core C — add it to \mathcal{K} and start over from top

IHS Toy Example (1/2)

- 1 Given same **PB formula F** and objective function

$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6$$

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$$\min x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5 + 6x_6$$

- 2 For

$$\mathcal{K}_1 = \emptyset$$

optimization solver returns minimal solution

$$\rho_1 = \{x_1 = x_2 = \dots = x_6 = 0\}$$

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- ③ Decision solver with assumptions ρ_1 returns PB core constraint

$$3x_2 + 2x_3 + x_4 + x_5 \geq 4$$

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- 4 For

$$\mathcal{K}_2 = \{3x_2 + 2x_3 + x_4 + x_5 \geq 4\}$$

optimization solver returns minimal solution

$$\rho_2 = \{x_2 = x_3 = 1; x_1 = x_4 = \dots = x_6 = 0\}$$

IHS Toy Example (2/2)

- 5 Decision solver with assumptions ρ_2 returns PB core constraint

$$x_2 + x_4 + x_5 + x_6 \geq 2$$

IHS Toy Example (2/2)

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- 6 For

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- 7 Decision solver with assumptions ρ_2 returns **SATISFIABLE**

IHS Toy Example (2/2)

- 5 Decision solver with assumptions ρ_2 returns PB core constraint

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- 6 For

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optimization solver returns minimal solution

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- 7 Decision solver with assumptions ρ_2 returns **SATISFIABLE**
- 8 Hence, we have found an optimal solution with objective value 6 (as for LSU and core-guided search)

Comparison of Core-Guided Search and IHS

Suppose solver with assumptions returns core

$$C \doteq x_1 + x_2 + x_3 + x_4 \geq 2$$

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Core-guided search

- Introduce new variables by
 $x_1 + x_2 + x_3 + x_4 = 2 + y_3 + y_4$
- Ignore all x_i with smallest weight in objective in next call (get cancelled when objective rewritten)
- Instead assume that “somehow $x_1 + x_2 + x_3 + x_4 \leq 2$ holds” (i.e., assume $y_3 = 0$)

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IHS

- Add C to collection of cores \mathcal{K}
- Find concrete assignment satisfying all of \mathcal{K} as cheaply as possible
- Try that assignment as starting point for next call to decision solver

Competitive Advantages of Core-Guided vs. IHS

- IHS and core-guided approaches for MaxSAT orthogonal [Bac21]
- For MaxSAT problems with many interchangeable soft clauses core-guided seems better (i.e., when it is not important exactly which of these clauses end up in the core)
- For MaxSAT problems with many distinct weights, IHS seems better

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Theoretical relations between IHS and core-guided search?

Provide a more precise theoretical comparison of IHS and core-guided search with simulations and/or separations

(Some theoretical work on related problems in, e.g., [FMSV20, MIB⁺19])

More Questions About Core-Guided Search and IHS

- 1 Use assumptions $\{\ell_j = 0 \mid \ell_j \notin H\}$ or add also $\{\ell_i = 1 \mid \ell_i \in H\}$ for pseudo-Boolean IHS? (The latter done in [SBJ21, SBJ22])
- 2 Use cores in pseudo-Boolean core-guided search for objective reformulation without converting to cardinality constraints first?
- 3 How to do core minimization/strengthening in a PB setting?
- 4 Use something other than IP solver for pseudo-Boolean “hitting set problem”?
- 5 **Abstract cores** [BBP20] used to get IHS plus core counting variables — is it possible to do **full integration of core-guided search and IHS** in same solver in meaningful way?
- 6 Certify correctness using proof logging? [*work in progress*]

Summing up

- MaxSAT can be attacked with combination of powerful tools
 - Core-guided solving
 - Implicit hitting set (IHS) solving
 - Integer linear programming
- Approaches with complementary strengths — room for synergies?
- Lifting core-guided and IHS algorithms to pseudo-Boolean setting presents opportunities and challenges
 - No need for CNF re-encoding
 - More powerful pseudo-Boolean reasoning
 - But also slower than clausal reasoning
 - And more degrees of freedom in algorithm design — more choices needed to get right
- Many interesting questions to explore – should provide rich pickings of low-hanging fruit

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Thank you for your attention!

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